



Thanks for purchasing *Turnigy*[®] *AQUASTAR ESC* speed controllers. *Turnigy*[®] *AQUASTAR ESC* are specifically developed to supply stable and strong power for r/c model boats beyond you expected. Please read the instruction booklet carefully before use.

Warnings

• Strongly **recommend** to calibrate the throttle range of transmitter when you first use the controller or when using a new/different transmitter or receiver.

• When connecting the ESC to battery pack, please ensure the polarity is correct. Incorrect polarity may cause permanent damage to the ESC and such damage is not covered by manufacturer's WARRANTY.

- When you use the ESC, turn on the transmitter BEFORE powering on the receiver.
- When you finish the running, power off the receiver BEFORE turning off the transmitter.
- Changing the PWM may cause the motor to heat ahead of time.

• Never disconnect the battery pack while the motor is running, as this could cause damage to the speed controller and/or motor.

• Connectors with low conductivity may cause erratic motor rotations or other unexpected movements.

• If you do not use the BEC function of the ESC and are using a separate receiver pack or UBEC to power receiver and servos instead, please disconnect the red wire from the ESC's receiver lead.

• The controller will automatically power off the motor if the battery voltage drops below the programmed cut-off voltage (factory preset at '6.0V').





I ESC Features

- · Microprocessor controlled, extremely low resistance
- Water-proof PCB, and aluminum water-cool thermal dissipation
- Full protection soft, include signal lose protection, temperature protection, motor block-up protection.
- Fully program by software on computer, or by Turnigy® LCD program box, or by TX stick

• The firmware of the ESC is upgradeable from Internet as the new version of the software becomes available.

• Compatible to use with both general board transmitters and pistol transmitters with programmable brake setting for any competitions.

Models	90A	120A	
Voltage	2~6 cells Lithium-Polymer OR 6~20cells NiCad/NiMH	2~6 cells Lithium-Polymer OR 6~20cells NiCad/NiMH	
Current/max	90amp continuous/110 amp surge	120amp continuous/150amp surge	
BEC	5V, 3.5A switching BEC, max 4A5V, 3.5A switching BEC, max 4A		
Dimensions	90mmx36mmx20mm	90mmx36mmx20mm	
Weight	97g (excl. cables)	100g (excl. cables)	

П <u>Specifications</u>

III Using the ESC

Connect ESC to motor, receiver and battery

- Please solder good quality golden bullet connectors to the wires of brushless motor and the three motor wires of ESC. Connect the ESC 's three motor wires to the brushless motor, swapping any of the two motor wires connection can change the motor's rotating direction.

- The quality and discharging capability of battery pack will influence the efficiency and rpm of motor. Please solder high conductive T connectors to the battery's (+) and (-)wires.

- Plug the receiver lead (small color wires)of ESC to the receiver (Usually Ch 2).



Calibrate the throttle range of transmitter (Recommend)

A. Board Style transmitter calibration

- Correctly connect the ESC with brushless motor, plug the receiver lead of ESC into receiver (usually into Channel 2);

- Put the throttle to the forward top position, turn on the transmitter;

- Power on the receiver, ESC and motor. There are 3 beeps emitted from the motor, which indicates all electronics are correctly power on for the setting.

- Then there are 4 long beeps emitted from the motor $\mathcal{I} \mathcal{I} \mathcal{I}$.

- During or after the 4 long beeps, move the throttle stick to the '0' position you want to set, at this point, you have calibrated the throttle range of your transmitter;

- Waiting one second, there will be two beeps , J emitted from the motor

- Calibration of throttle is completed.

Note: 1. Recommend the '0' position should not be set higher beyond the 50%.

2. Motor is needed to install for acoustic guide. Meanwhile, please keep the propeller away from human beings or any objects.

B. <u>Pistol style transmitter calibration</u>

- Correctly connect the ESC with brushless motor, plug the receiver lead of ESC into receiver (usually into Channel 2);

- Put the throttle to the forward full position, turn on the transmitter;

- Power on the ESC, there are 3 beeps emitted from the motor, which indicates all electronics are correctly power on for the setting.

- Then there are 4 long beeps emitted from the motor $\Im \Im \Im \Im$.

- Following two beeps are powering beeps, it is time to go now!

Program the ESC

The Turnigy® Aquastar ESC programmable settings

LVC	Auto*	5.0V	6.0V (2 Lipo)	7.2V	8.4V	9.0V (3 Lipo)	12.0V (4 Lipo)	15.0V (5 Lipo)	18.0V (6 Lipo)
Brake Type	Clo	ose *	Soft	brake					
Timing Advance	Low		Middle		E	High		Auto *	
Cutoff Type	Hard cutoff *		Soft cutoff						
Startup Type	Soft start		Standard *		Fast start				
PWM Rate	8KHz *		12KHz		16KHz				
Throttle Range	640	uS							

Note: 1. Parameters with asterisk * behind is the default settings of ESC. LVC Is preset In '6.0V' In factory.

- 2. The throttle range can be read on PC after installing 'Turnigy[®] Aquastar ESC' software. It is Auto changed after calibrating the throttle range of transmitters.
- 3. When use Lipo-Polymer battery pack, please carefully set the LVC to efficiently protect the battery against discharging.





A. Program by TX stick

Turnigy[®] ESC support to fully program by TX stick, please refer to the setting diagram in the last page.

B. Program by Turnigy® LCD Program box

Program box is auto identify the ESC model and clearly display the corresponding programmable parameters in LCD. It is pocket size and conveniently take to use at fields. Please read the instructions of Program box to correctly set the *Turnigy*[®] ESC.

C. Program by software 'Turnigy® Aquastar ESC' on PC.

The set-up software of '*Turnigy*[®] Program' is recorded in a CD and always attached with each *Turnigy*[®] ESC. You must install the software on PC. Please refer to the \mathbb{N} sections.

It Is ready to go now!

- After changing the ESC's parameters, It Is suggested to firstly have a test on the testbed before assembling It to hull so that to choose appropriate settings for the matched power configuration. *Please always keep the prop far away from human and objects In testing.*

- Reconnect the ESC to battery, the green LED on ESC will light for a second. And two beeps emitting out from motor while Indicates to successfully detect the signal. Then It Is time to go now.

NOTE: If the LVC of ESC Is set In "Auto', after the two beeps there will follow beeps to detect the Lipo cells while the red LED flashing.





IV Installing Software to PC

System requirement

- A. Personal Computer with WINDOWS 2000 or WINDOWS XP operation system
- B. CD-ROM drive (or access to Internet)
- C. USB port available
- D. 4 Megabytes hard disk space
- E. Computer screen resolution with 800×600, 1024×768 (*Recommend*), 1280×1024.

Hardware

The hardware include a *Turnigy*[®] boat ESC, USB Linker, Set-up CD.







ESC 90A/120A

USB Linker

Set-up CD

STEPS to install the soft:

- Insert the CD in the CD driver of the computer.
- Double click the 'Turnigy Aquastar ESC setup. exe'













Program the ESC

Please refer to the label of USB Linker and correctly connect the receiver lead of ESC to USB Linker.

Connect the USB Linker to one of the available USB ports of PC. A little red LED on USB Linker will light up. The green LED on the controller would light up while connecting is successful other wise not.

NOTE: Never plug the USB Linker to USB port of PC BEFORE installation of software is successfully completed.

When successfully connect to PC, the computer will automatically recognize a 'com port' as the name "CP210×USB to UART Bridge Controller", please find the correct 'com port' number on you PC in this way.

The com port is generally 'com 3' or 'com 4,' but there are different 'com port' on different computers. You can find the accurate com port on your computer in this way: Click the right button of mouse the icon 'My Computer' \rightarrow Manage \rightarrow Device Manager \rightarrow Ports(Com & LPT). The 'com port' after "CP210 × USB to UART Bridge Controller" is the right one.



Note: If you cannot find such kind of 'com port' in the 'Device Manager', please check whether the connection of ESC to USB Linker is correct and ensure they are tightly connected without any loose. If they are both right, the problem is probably that the software has not been successfully installed on your PC. Please Install the soft again.



Single left click the down arrow to choose the parameter you want to set.

🗲 Turnigy Aquastar ESC		×
COM Port Option	Parameters	
Comm3 🔽 Open	LVC:	6.0V(2 Lipe)
Connect Status Connect	Brake Types:	6.07(2 Lipo) 7.2V 8.4V 9.0V(3 Lipo) 12.0V(4 Lipo)
Programing Operation	Timing Adance:	15. 0V (5 Lipo) 18. 0V (6 Lipo)
Reading Data from ESC	Cutoff Type:	Hard Cutoff 📃 💌
Back to Default	Startup Type:	Standard 💌
	PWM Rate:	8KHz 💌
Model of Turnigy Aquastar ESCs	Throttle Range:	720 uS
		Update
Firmware Version of Turnigy Aquas	star ESC	
DTuB 9C22 01MC	1200	EXIT

Click the 'Update' button to save the modification.

NOTE: Please set the parameters always after current parameters of ESC is displayed in window and according to the instructing turn, otherwise programming of ESC will be defeated and ESC will still keep the parameters set in last time.

Upgrade the firmware of ESC

- Click 'Start' to get into 'Programs'
- Choose and click 'Turnigy ESC for Boat', and click 'Turnigy Aquastar ESC Upgrade'
- Input the correct 'Com port', click '**Open'** button.
- Single left click 'Get ESC's Ver' to read out the version number of the ESC.



🗲 Turnigy Aquastar ESC Upgrade	×
Specify the upgrade file Open Version of the firmware:	COM port Option Comm3 • Open
Current version of Turnigy Aquastar ESC Get ESC's Ver DTuB 9C22 01MC 1200	Upgrade Status Start Status: EXIT

- Single left click **'Open'** to open the latest upgradeable firmware, which can be downloaded from website once a new one is released.

- Click 'Start' to upgrade the firmware of ESC to the latest, it will be completed in 3-5 seconds.





Turnigy[®] Aquastar ESC settings' features

• Low Cut-off Voltage

Option 1:Auto Lipo	Auto Lipo Cells Detecting
Option2:6.0V(default)	6-8 cell NiCad or NiMH packs, or 2 cell Lithium packs
Option 3:7.2V	8 cell NiCad or NiMH packs, or 2 cell Lithium packs
Option 4:8.4V	9 cell NiCad or NiMH packs
Option 5:9.0V	10 cell NiCad or NiMH packs, or 3 cell Lithium packs
Option 6:12.0V	4 Lipo cells
Option 7:15.0V	5 Lipo cells
Option 8:18.0v	6 Lipo cells

NOTE: Low Cut-off Voltage can protect the main battery from being discharged too low, and provide the normal operating voltage to receiver and servos.

• Brake Type

Option 1:Brake disabled	Brake disabled is mainly used for helicopters.
(default)	
Option 2:Soft brake	Soft brake provides 50% of full braking power.
Option 3:Hard brake	Hard brake is 70% braking power. Direct drive applications where more braking power is required. Hard brake should only be used below 12V.

• Timing Advance

Option 1: Low advance timing	Recommended for more lower pole count motors. Gives more power and			
0°~15°	slightly less efficient.			
Option 2: middle advance timing	Recommended for most motors .Gives a good balance of power and efficiency.			
5 °~ 20 °				
Option 3: High advance timing	Recommended for most of higher pole count motors			
15° ~ 30 °				
Option4:Auto(default)	Recommended for most of all brushless motors.			



• Cutoff Type

Option 1 :Hard cutoff (default)	When battery voltage reaches cut-off voltage the motor will shutdown				
	immediately. Motor can be restarted by closing the throttle to the lowest position				
	and then move the throttle as normal				
Option 2: Soft cutoff	When battery voltage reaches cut-off voltage, the ESC will slowly reduce motor				
	power to zero, you will notice a decrease in power and it is time to land, the				
	throttle maintains its full linear response.				

NOTE: Soft cutoff is always automatically active in Governor Mode.

• Start Type

Option 1: soft start	Very soft and smoothly start the motor, it will takes more time
Option 2:standard start (default)	Start the motor at normal speed
Option 3: Fast start	Fast star up, recommended to use it for racing.

• PWM Switching Rate

Option 1:8KHz(default)	Recommended for most brushless motors
Option 2: 12KHz	Recommended for low inductance motors
Option 3: 16KHz	Recommended for very low inductance motors

Note: we strongly recommend only the experienced modeler could change this setting.

correctly power on for the setting. Correctly cc the ESC ESC n transmitter; power turn the throttle to the and receiver. Move the motor, which beeps emitted from highest position, brushless There are three the receiver, and on connect motor. motor with the ᡟ beeps emitted from the motor There are 4 |___ |__ programmable setting entered already indicate beeps you have the One beep indicates you have entered the Low Cutoff Voltage Setting. 6th beep:9.0v 4th beep:7.2v 9th beep: 18.0V 8th beep:15.0v 5th beep:8.4v 3rd beep:6.0v 1st beep:Auto (default) 7th beep:12.0v 2nd beep:5.0v i beep: Low Cutoff Voltage The __st The beep: None := 2_{nd} •_ 1st beep: Close (default) Three beeps indicates you have entered the Brake Type Setting. 2nd beep: Soft Brake beep: Brake Type The Ξ ಜ್ಷ Move the throttle to the highest position Three beeps emitted from motor indicated your setting is successful 4th beep: Auto (default) Four beeps indicates you have entered the Timing Advance Setting. 3rd beep:High 2ndbeep:Middle 1st beep:Low beep: Timing Advance The Move the throttle to the lowest position 4 5 Main Loop Five beeps indicates you have entered the Cutoff Type Setting. 2nd beep: Soft Cutoff 1st beep: Hard Cutoff (default) beep: Cutoff Type The പ്ല Six beeps indicates you have entered the Soft Start Setting. 3rd beep: Fast Start 2nd beep: Standard ((default) 1st beep: Soft Start beep: Start Type The 6th Start The beep: None **۲** PWM
Switching
Rate Eight beeps indicates you have entered the PWM Switching Rate Setting. The beep: 1st beep: 8K (default) 3rd beep:16K 2nd beep:12K °≞ reserve GO beep: EXIT The 10th i |__

Figure. 1 : Operational Flowchart for Programming the ESC with Throttle